

Taylor Expansions and Numerical Approximations for Stochastic Partial Differential Equations

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- 1 Taylor expansions for SODEs
- 2 Taylor expansions for SPDEs
- 3 A new numerical method for SPDEs with non-additive noise
- 4 A new numerical method for SPDEs with additive noise

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Consider the SODE:

$$dX_t = f(X_t) dt + g(X_t) dW_t,$$

which is understood as

$$X_t = X_0 + \int_0^t f(X_s) ds + \int_0^t g(X_s) dW_s$$

\mathbb{P} -a.s. for all $t \in [0, T]$. Applying Itô's formula to the integrands above yields

$$\begin{aligned} X_t &\approx X_0 + f(X_0) \cdot t + g(X_0) \cdot \int_0^t dW_s + g'(X_0) g(X_0) \cdot \int_0^t \int_0^s dW_u dW_s \\ &= X_0 + f(X_0) \cdot t + g(X_0) \cdot W_t + \frac{1}{2} \cdot g'(X_0) g(X_0) \cdot ((W_t)^2 - t) \quad \mathbb{P}\text{-a.s.} \end{aligned}$$

Milstein's approximation (1974).

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Reconsider Milstein's approximation:

$$X_t \approx X_0 + f(X_0) \cdot t + g(X_0) \cdot W_t + \frac{1}{2} \cdot g'(X_0) g(X_0) \cdot ((W_t)^2 - t)$$

The corresponding numerical scheme, the so-called **Milstein scheme** (or also Taylor scheme of (strong) order 1.0), is then given by $Y_0^N = X_0$ and

$$\begin{aligned} Y_{n+1}^N = Y_n^N + f(Y_n^N) \cdot \frac{T}{N} + g(Y_n^N) \cdot \left(W_{\frac{(n+1)T}{N}} - W_{\frac{nT}{N}} \right) \\ + \frac{1}{2} \cdot g'(Y_n^N) g(Y_n^N) \cdot \left(\left(W_{\frac{(n+1)T}{N}} - W_{\frac{nT}{N}} \right)^2 - \frac{T}{N} \right) \end{aligned}$$

for every $n \in \{0, 1, \dots, N-1\}$, $N \in \mathbb{N}$ and is of (strong) order 1.

It is very easy to simulate and impressively efficient for one-dimensional SODEs in comparison to e.g. Euler's method which is of (strong) order $\frac{1}{2}$.

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The general theory of Taylor expansions for SODEs and the numerical schemes based on them can be found in the monographs

- Kloeden & Platen (1992)
- Milstein (1995)

(Stochastic Taylor expansions).

Essential constituents:

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Method for deriving Taylor expansions:

- Iterated application of the stochastic fundamental theorem of calculus, i.e. Itô's formula.

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Itô's formula for SPDEs? In general not a semi-martingale

Let $(H, \|\cdot\|)$ be a reasonable state space of a SPDE.

- Krylov & Rozovskii (1979): Itô formula for $F : H \rightarrow \mathbb{R}$, $F(v) = \|v\|^2$, $v \in H$, with powerful consequences to the variational approach, see also Gyöngy & Krylov (1981) and Prévot & Röckner (2007)
- Gradinaru, Nourdin & Tindel (2005): Itô formula for $F : H \rightarrow \mathbb{R}$ smooth
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For the Taylor expansion approach for SODEs, one would need an Itô formula for $F : H \rightarrow \mathbb{R}$ smooth.

If the solution of the SPDE is spatially smooth and the solution is a semi-martingale, then Taylor expansions & Taylor schemes for SPDEs in

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For the Taylor expansion approach for SODEs, one would need an Itô formula for $F : H \rightarrow \mathbb{R}$ smooth.

If the solution of the SPDE is spatially smooth and the solution is a semi-martingale, then Taylor expansions & Taylor schemes for SPDEs in

- Grecksch & Kloeden (1996), see also Kloeden & Shott (2001)
- Buckdahn & Ma (2002)
- Lord & Rougemont (2004)

SPDE Setting

Fix $T > 0$, a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ with normal filtration $(\mathcal{F}_t)_{t \in [0, T]}$ and two \mathbb{R} -Hilbert spaces H and U .

(A1) Let $\underline{A : D(A) \subset H \rightarrow H}$ be a bijective linear operator with negative compact inverse.

(A2) Let $\underline{W : [0, T] \times \Omega \rightarrow U}$ be a standard Q -Wiener process with covariance operator $Q : U \rightarrow U$. Let $U_0 := Q^{\frac{1}{2}}(U)$.

(A3) Let $\underline{F : D((-A)^\beta) \rightarrow H}$ and $\underline{B : D((-A)^\beta) \rightarrow HS(U_0, H)}$ with $\beta \in [0, 1)$ be twice continuously Fréchet differentiable with appropriate globally bounded derivatives.

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Consider the SPDE

$$dX_t = \left[AX_t + F(X_t) \right] dt + B(X_t) dW_t, \quad X_0 = \xi$$

for $t \in [0, T]$.

SPDE in the mild form

$$X_t = e^{At} \xi + \int_0^t e^{A(t-s)} F(X_s) ds + \int_0^t e^{A(t-s)} B(X_s) dW_s$$

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Example

Let $d \in \mathbb{N}$ and consider the SPDE

$$dX_t(x) = \left[\kappa \Delta X_t(x) + f(x, X_t(x)) \right] dt + b(x, X_t(x)) dW_t(x)$$

with $X_t|_{\partial(0,1)^d} \equiv 0$ and $X_0(x) = \xi(x)$ for $x \in (0, 1)^d$ and $t \in [0, T]$. Here

- $U = H = L^2((0, 1)^d, \mathbb{R})$,
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\mathbb{P} -a.s. for all $t \in [0, T]$. Subtracting X_0 gives

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$$X_t \approx e^{At} X_0 + \int_0^t e^{A(t-s)} B(X_0) dW_s$$

Consider

$$\Delta X_t = (e^{At} - I) X_0 + \int_0^t e^{A(t-s)} F(X_s) ds + \int_0^t e^{A(t-s)} B(X_s) dW_s$$

\mathbb{P} -a.s. for all $t \in [0, T]$. Omitting first and second summand yields the first simple Taylor approximation for SPDEs

$$\Delta X_t \approx \int_0^t e^{A(t-s)} B(X_0) dW_s, \quad \text{i.e.}$$

$$X_t \approx X_0 + \int_0^t e^{A(t-s)} B(X_0) dW_s$$

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\mathbb{P} -a.s. for all $t \in [0, T]$. Classical Taylor approximations $F(X_s) \approx F(X_0)$ and $B(X_s) \approx B(X_0)$ yield

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Exponential Euler approximation (see the final section for more details).

Consider

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Infinite dimensional analog of Milstein's approximation (see the next section of this talk)

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Infinite dimensional analog of Milstein's approximation (see the next section of this talk)

Iterating this idea yields more Taylor approximations such as

$$\begin{aligned}
 X_t \approx & e^{At} X_0 + \int_0^t e^{A(t-s)} F(X_0) ds + \int_0^t e^{A(t-s)} B(X_0) dW_s \\
 & + \int_0^t e^{A(t-s)} B'(X_0) (e^{As} - I) X_0 dW_s \\
 & + \int_0^t e^{A(t-s)} B'(X_0) \left(\int_0^s e^{A(s-u)} B(X_0) dW_u \right) dW_s \\
 & + \frac{1}{2} \int_0^t e^{A(t-s)} B''(X_0) \left(\int_0^s e^{A(s-u)} B(X_0) dW_u, \int_0^s e^{A(s-u)} B(X_0) dW_u \right) dW_s
 \end{aligned}$$

Some remarks:

- References:
 - “Taylor expansions of solutions of stochastic partial differential equations with additive noise” (J & Kloeden; Ann. Probab. 2010)
 - “Taylor expansions of solutions of stochastic partial differential equations” (J; DCDS B 2010)
- Systematic theory with appropriate integral operators
- Precisely description of the remainder terms & arbitrarily high orders
- Essential constituents: $\int_0^t e^{A(t-s)} B'(X_0) \left(\int_0^s e^{A(s-u)} B(X_0) dW_u \right) dW_s$
- Method: classical Taylor expansions in Banach spaces & recursion technique
- These Taylor Expansions for SPDEs generalize the Taylor Expansions for ODEs and SODEs.

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Content

- 1 Taylor expansions for SODEs
- 2 Taylor expansions for SPDEs
- 3 A new numerical method for SPDEs with non-additive noise**
- 4 A new numerical method for SPDEs with additive noise

Reconsider the SPDE and the infinite dimensional analog of Milstein's approximation

Reconsider the SPDE

$$dX_t = \left[AX_t + F(X_t) \right] dt + B(X_t) dW_t, \quad X_0 = \xi$$

for $t \in [0, T]$. SPDE in the mild form

$$X_t = e^{At} X_0 + \int_0^t e^{A(t-s)} F(X_s) ds + \int_0^t e^{A(t-s)} B(X_s) dW_s$$

\mathbb{P} -a.s. for all $t \in [0, T]$. Infinite dimensional analog of Milstein's approximation:

$$\begin{aligned} X_t \approx & e^{At} X_0 + \int_0^t e^{A(t-s)} F(X_0) ds + \int_0^t e^{A(t-s)} B(X_0) dW_s \\ & + \int_0^t e^{A(t-s)} B'(X_0) \left(\int_0^s e^{A(s-u)} B(X_0) dW_u \right) dW_s \end{aligned}$$

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Reconsider the SPDE and the infinite dimensional analog of Milstein's approximation

Reconsider the SPDE

$$dX_t = \left[AX_t + F(X_t) \right] dt + B(X_t) dW_t, \quad X_0 = \xi$$

for $t \in [0, T]$. SPDE in the mild form

$$X_t = e^{At} X_0 + \int_0^t e^{A(t-s)} F(X_s) ds + \int_0^t e^{A(t-s)} B(X_s) dW_s$$

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A one-dimensional example SPDE

Let $d = 1$ and consider the SPDE

$$dX_t(x) = \left[\kappa \frac{\partial^2}{\partial x^2} X_t(x) + f(x, X_t(x)) \right] dt + b(x, X_t(x)) dW_t(x)$$

with $X_t(0) = X_t(1) = 0$ and $X_0(x) = \xi(x)$ for $x \in (0, 1)$ and $t \in [0, T]$
with the covariance operator $Q : H \rightarrow H$ given by

$$(Qv)(x) = \sum_{j=1}^{\infty} \frac{2}{j^3} \cos(j\pi x) \int_0^1 \cos(j\pi y) v(y) dy$$

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Goal: Solve the strong approximation problem, i.e. compute $Y : \Omega \rightarrow H$ such that

$$\left(\mathbb{E} \left[\int_0^1 |X_T(x) - Y(x)|^2 dx \right] \right)^{\frac{1}{2}} < \varepsilon$$

holds for a given precision $\varepsilon > 0$ with the least possible computational effort.

Spectral Galerkin approximations: $P_N : H \rightarrow H$, $N \in \mathbb{N}$, given by

$$(P_N(v))(x) = \sum_{n=1}^N 2 \sin(n\pi x) \int_0^1 \sin(n\pi y) v(y) dy$$

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$Z_n^N : \Omega \rightarrow P_N(H)$, $n \in \{0, 1, \dots, N^4\}$, $N \in \mathbb{N}$, given by $Z_0^N = P_N(\xi)$ and

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Linear implicit Euler scheme and spectral Galerkin approximations

Theorem (e.g. Hausenblas, 2003)

There exist $C_r > 0$, $r \in (0, 2)$, such that

$$\left(\mathbb{E} \left[\int_0^1 |X_T(x) - Z_{N^4}^N(x)|^2 dx \right] \right)^{\frac{1}{2}} \leq C_r \cdot N^{(r-2)}$$

holds for all $N \in \mathbb{N}$ and all arbitrarily small $r \in (0, 2)$.

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A new algorithm for SPDEs with non-additive noise

Reconsider the infinite dimensional analog of Milstein's approximation

$$X_t \approx e^{At} X_0 + \int_0^t e^{A(t-s)} F(X_0) ds + \int_0^t e^{A(t-s)} B(X_0) dW_s \\ + \int_0^t e^{A(t-s)} B'(X_0) \left(\int_0^s e^{A(s-u)} B(X_0) dW_u \right) dW_s$$

Approximating the semigroup yields

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A new algorithm for SPDEs with non-additive noise

Reconsider the infinite dimensional analog of Milstein's approximation

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Theorem (J & Röckner, 2010)

There exist $C_r > 0$, $r \in (0, 2)$, such that

$$\left(\mathbb{E} \left[\int_0^1 |X_T(x) - Y_{N^2}^N(x)|^2 dx \right] \right)^{\frac{1}{2}} \leq C_r \cdot N^{(r-2)}$$

holds for all $N \in \mathbb{N}$ and all arbitrarily small $r \in (0, 2)$.

- $Y_{N^2}^N$ converges to X_T with order 2–
- N^3 random variables are needed to simulate $Y_{N^2}^N$
- Conclusion: about $O(\varepsilon^{-\frac{3}{2}})$ random variables are needed to achieve the desired precision $\varepsilon > 0$

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Numerical example

Consider the SPDE

$$dX_t(x) = \left[\frac{1}{20} \frac{\partial^2}{\partial x^2} X_t(x) + 1 - X_t(x) \right] dt + \frac{X_t(x)}{1 + X_t(x)^2} dW_t(x)$$

with $X_t(0) = X_t(1) = 0$ and $X_0(x) = 0$ for $x \in (0, 1)$ and $t \in [0, T]$ with $T = 1$.

We plot

$$\left(\mathbb{E} \left[\int_0^1 |X_T(x) - Z_{N^4}^N(x)|^2 dx \right] \right)^{\frac{1}{2}}$$

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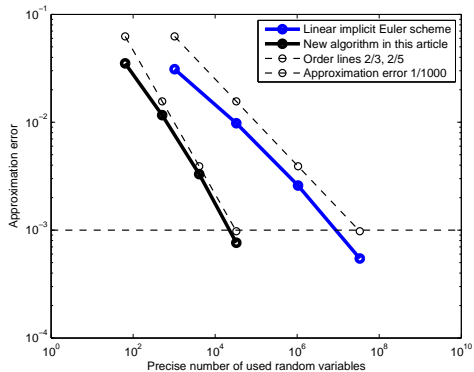
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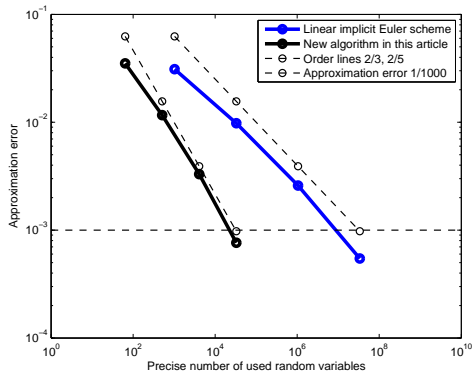
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A two-dimensional stochastic heat equation

Let $d = 2$ and consider the SPDE

$$dX_t(x_1, x_2) = \left[\frac{1}{50} \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} \right) X_t(x_1, x_2) \right] dt + X_t(x_1, x_2) dW_t(x_1, x_2)$$

with $X_t|_{\partial(0,1)^2} \equiv 0$ and $X_0(x_1, x_2) = 2 \sin(\pi x_1) \sin(\pi x_2)$ for $x_1, x_2 \in (0, 1)$ and $t \in [0, 1]$ with the covariance operator $Q : H \rightarrow H$ given by

$$(Qv)(x_1, x_2) = \sum_{j_1, j_2=1}^{\infty} \frac{2 \sin(j_1 \pi x_1) \sin(j_2 \pi x_2)}{(j_1 + j_2)^4} \int_0^1 \int_0^1 \sin(j_1 \pi y_1) \sin(j_2 \pi y_2) v(y_1, y_2) dy_1 dy_2$$

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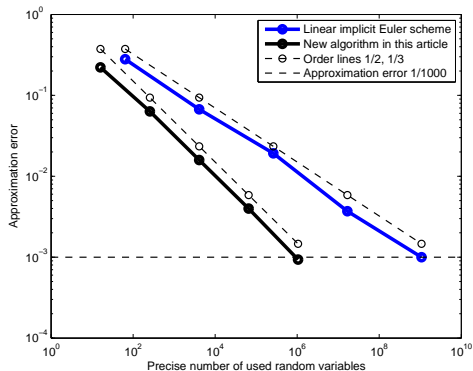
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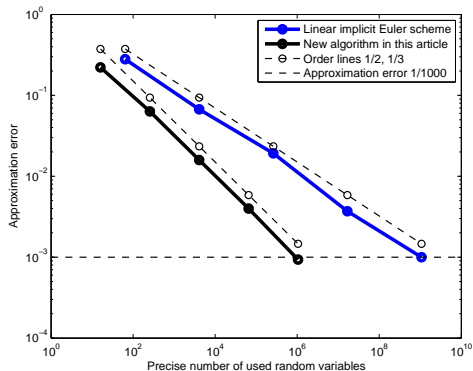
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Reference: "A Break of the Complexity of the Numerical Approximation of Nonlinear SPDEs with Multiplicative Noise" (J & Röckner; arXiv 2010)



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Content

- 1 Taylor expansions for SODEs
- 2 Taylor expansions for SPDEs
- 3 A new numerical method for SPDEs with non-additive noise
- 4 A new numerical method for SPDEs with additive noise**

Reconsider the SPDE and the Exponential Euler approximation

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$$dX_t = \left[AX_t + F(X_t) \right] dt + B(X_t) dW_t, \quad X_0 = \xi$$

for $t \in [0, T]$. SPDE in the mild form

$$X_t = e^{At} X_0 + \int_0^t e^{A(t-s)} F(X_s) ds + \int_0^t e^{A(t-s)} B(X_s) dW_s$$

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A stochastic Ginzburg-Landau PDE with additive space-time white noise

Consider the SPDE

$$dX_t(x) = [\Delta X_t(x) + X_t(x) - X_t(x)^3] dt + dW_t(x)$$

with $X_t(0) = X_t(1) = 0$ and $X_0 = 0$ for $x \in (0, 1)$ and $t \in [0, T]$ on $H = L^2((0, 1), \mathbb{R})$ with $T = 1$ and where $(W_t)_{t \in [0, T]}$ is a cylindrical I -Wiener process on H here.

Goal: Compute

$$X_T(\omega, x), \quad x \in [0, 1],$$

with the precision of two decimals, i.e. with the precision $\varepsilon = \frac{1}{100}$, for one random $\omega \in \Omega$.

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Linear implicit Euler scheme and spectral Galerkin approximations

$Z_n^N : \Omega \rightarrow P_N(H)$, $n \in \{0, 1, \dots, N^2\}$, $N \in \mathbb{N}$, given by $Z_0^N = 0$ and

$$Z_{n+1}^N = \left(I - \frac{T}{N^2} A \right)^{-1} \left(Z_n^N + \frac{T}{N^2} \cdot (P_N F)(Z_n^N) + \int_{\frac{nT}{N^2}}^{\frac{(n+1)T}{N^2}} P_N dW_s \right)$$

\mathbb{P} -a.s. for all $n \in \{0, 1, \dots, N^2 - 1\}$ and all $N \in \mathbb{N}$.

- N^2 time steps are used in $(Z_n^N)_{n \in \{0, 1, \dots, N^2\}}$
- $Z_n^N \in P_N(H)$ for all $n \in \{0, 1, \dots, N^2\}$ and $P_N(H)$ is N -dimensional

-

$$\underbrace{N^2}_{\text{time steps}} \cdot \underbrace{N}_{\dim(P_N(H))} = N^3 \quad \text{independent standard normal random variables needed to simulate } Z_{N^2}^N \approx X_T$$

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Numerical results

We plot

$$\sup_{x \in [0,1]} \left| X_T(\omega, x) - Z_{N^2}^N(\omega, x) \right|$$

and

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for different $N \in \mathbb{N}$ and one random $\omega \in \Omega$.

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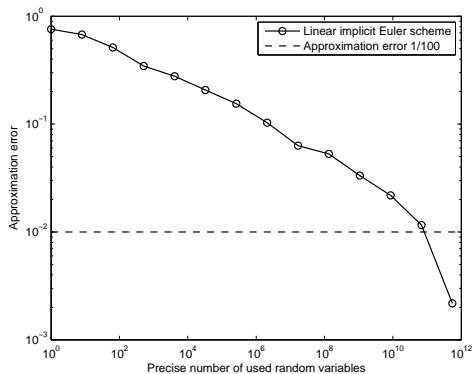
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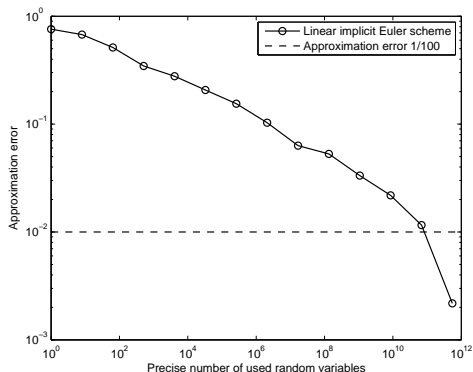
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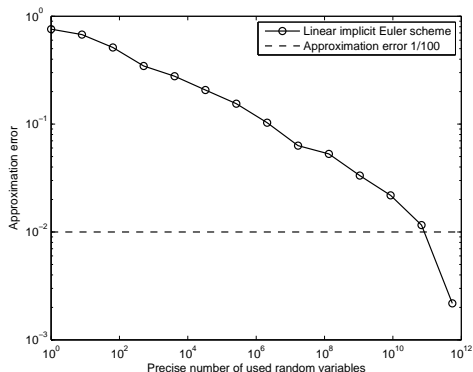
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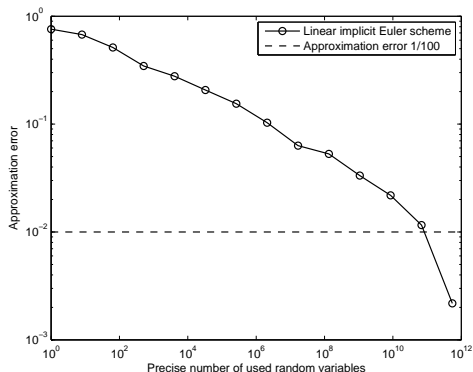
Linear implicit Euler scheme: $Z_{N^2}^N$ with $N = 8192$ ($N^3 = 8193^3 \approx 0.5 \cdot 10^{12}$ random variables) achieves the desired precision $\varepsilon = \frac{1}{100}$



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MATLAB code for $Z_{N^2}^N$ with $N = 8192$

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1 N = 8192; M = 67108864; A = -pi^2*(1:N).^2; Y = zeros(1,N);
2 for m=1:M
3     y = dst(Y) * sqrt(2);
4     Y = (Y + idst(y-y.^3)/sqrt(2)/M + randn(1,N)/sqrt(M))./(1 - A/M);
5 end
6 plot( (0:N+1)/(N+1), [0, dst(Y)*sqrt(2), 0] );

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CPU time on an INTEL PENTIUM D (3.0 GHz):

Linear implicit Euler scheme: \approx **6 days and 22 hours**

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6 plot( (0:N+1)/(N+1), [0, dst(Y)*sqrt(2), 0] );
```

CPU time on an INTEL PENTIUM D (3.0 GHz):

Linear implicit Euler scheme: \approx 6 days and 22 hours

MATLAB code for $Z_{N^2}^N$ with $N = 8192$

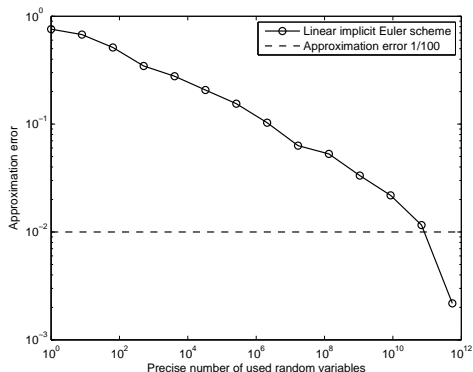
```

1 N = 8192; M = 67108864; A = -pi^2*(1:N).^2; Y = zeros(1,N);
2 for m=1:M
3     y = dst(Y) * sqrt(2);
4     Y = (Y + idst(y-y.^3)/sqrt(2)/M + randn(1,N)/sqrt(M))./(1 - A/M);
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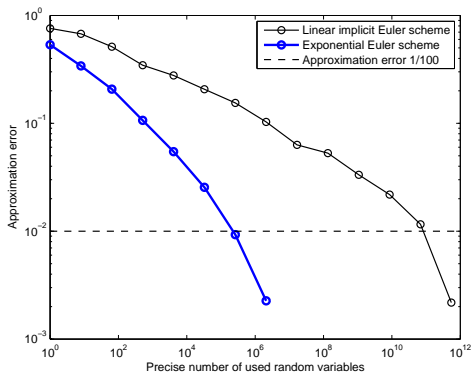
```

CPU time on an INTEL PENTIUM D (3.0 GHz):

Linear implicit Euler scheme: \approx **6 days and 22 hours**

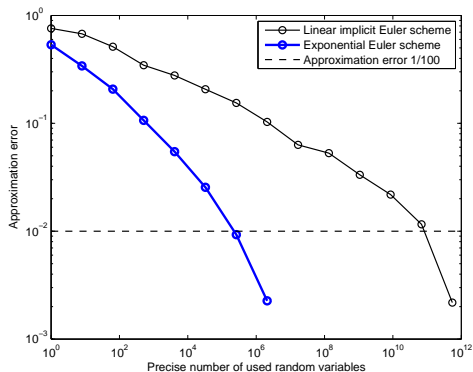


Linear implicit Euler scheme: $Z_{N^2}^N$ with $N = 8192$ ($N^3 = 8193^3 \approx 0.5 \cdot 10^{12}$ random variables) achieves the desired precision $\varepsilon = \frac{1}{100}$



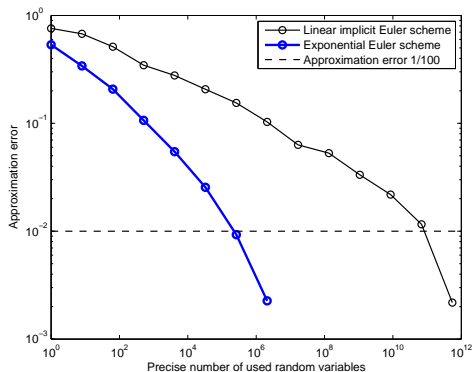
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Exponential Euler scheme: Y_N^N with $N = 64$ ($N^3 = 64^3 \approx 2.6 \cdot 10^5$ random variables) achieves the desired precision $\varepsilon = \frac{1}{100}$



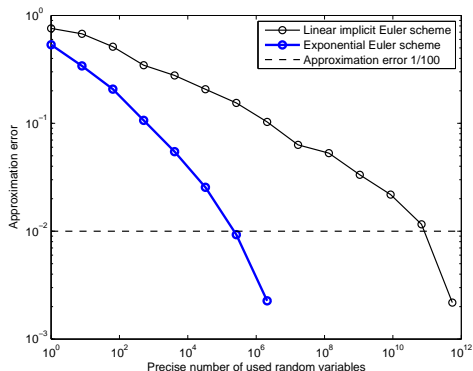
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Linear implicit Euler scheme: $Z_{N^2}^N$ with $N = 8192$ ($N^3 = 8193^3 \approx 0.5 \cdot 10^{12}$ random variables) achieves the desired precision $\varepsilon = \frac{1}{100}$

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Linear implicit Euler scheme: $Z_{N^2}^N$ with $N = 8192$ ($N^3 = 8193^3 \approx 0.5 \cdot 10^{12}$ random variables) achieves the desired precision $\varepsilon = \frac{1}{100}$

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MATLAB code for Y_N^N with $N = 64$

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1 N = 8192; M = 67108864; A = -pi^2*(1:N).^2; Y = zeros(1,N);
2 for m=1:M
3     y = dst(Y) * sqrt(2);
4     Y = (Y + idst(y-y.^3)/sqrt(2)/M + randn(1,N)/sqrt(M))./(1 - A/M);
5 end
6 plot( (0:N+1)/(N+1), [0,dst(Y)*sqrt(2),0] );
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Linear implicit Euler scheme: \approx **6 days and 22 hours**

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6 end
7 plot( (0:N+1)/(N+1), [0, dst(Y)*sqrt(2), 0] );

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CPU time on an INTEL PENTIUM D (3.0 GHz):

Linear implicit Euler scheme: \approx **6 days and 22 hours**

MATLAB code for Y_N^N with $N = 64$

```

1  N = 4096; M = 67108864; A = -pi^2*(1:N).^2; Y = zeros(1,N);
2  Q = sqrt((exp(2*A/M) - 1)/2./A);
3  for m=1:M
4      y = dst(Y) * sqrt(2);
5      Y = exp(A/M).*Y+(exp(A/M) - 1)./A.*idst(y-y.^3)/sqrt(2)+Q.*randn(1,N);
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```

CPU time on an INTEL PENTIUM D (3.0 GHz):

Linear implicit Euler scheme: \approx **6 days and 22 hours**

Exponential Euler scheme: \approx **0.48 seconds**

References:

- “Overcoming the order barrier in the numerical approximation of stochastic partial differential equations with additive space-time noise” (J & Kloeden; Proc. Roy. Soc. Lond. A 2009)
- “Efficient simulation of nonlinear parabolic SPDEs with additive noise” (J, Kloeden & Winkel; Ann. Appl. Probab. 2010)